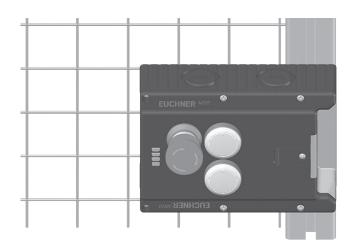
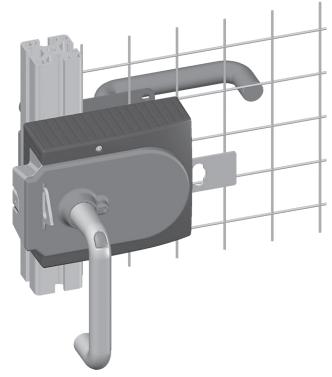
# **EUCHNER**

## **Operating Instructions**





Safety Systems

MGB-L1...-AR.-... / MGB-L2...-AR.-... MGB-L1...-AP.-... / MGB-L2...-AP.-... from V3.0.0



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#### 1. About this document

## 1.1. Scope

These operating instructions are valid for all MGB-L1...-AR.-... / MGB-L2...-AR.-... and MGB-L1...-AP.-... / MGB-L2...-AP.-.... These operating instructions, the document "Safety information and maintenance" and any enclosed data sheet form the complete user information for your device.

| Series | Guard locking types                  | System families | Product versions |
|--------|--------------------------------------|-----------------|------------------|
|        | L1 (guard locking by spring force)   | AP              | from V3.0.0      |
| MGB    | LI (guard lockling by Spring force)  | AR              |                  |
| IVIGD  | (avoid la dina hy adapaid favos)     | AP              |                  |
|        | L2 (guard locking by solenoid force) | AR              |                  |

#### 1.1.1. Notes on older product versions

Products with lower product versions or without a version number are not described by these operating instructions. Please contact our support team in this case.

## 1.2. Target group

Design engineers and installation planners for safety devices on machines, as well as setup and servicing staff possessing special expertise in handling safety components

## 1.3. Key to symbols

| Symbol/depiction       | Significance  |
|------------------------|---|
| AP                     | This section applies on operation as MGB-AP   |
| AR                     | This section applies on operation as MGB-AR   |
| DIP                    | In this section attention must be paid to the DIP switch setting  |
|                        | Printed document  |
| (www)                  | Document is available for download at www.euchner.de  |
| <b>S</b>               | Document on CD  |
| DANGER WARNING CAUTION | Safety precautions  Danger of death or severe injuries  Warning about possible injuries  Caution Slight injuries possible |
| NOTICE<br>Important!   | Notice about possible device damage Important information   |
| Tip                    | Tip/useful information  |



## 1.4. Supplementary documents

The overall documentation for this device consists of the following documents:

| Document title (document number)  | Contents  |          |
|---|---|----------|
| Safety information and<br>maintenance for safety<br>system MGB-AR/MGB-AP<br>from V3.0.0<br>(123151) | Basic information about safe setup and maintenance      |          |
| Operating instructions (119167)   | (this document)   | <b>S</b> |
| Possibly enclosed data sheet  | Item-specific information about deviations or additions |          |
| Brief instructions for teach-<br>in operation – MGB-AP/<br>MGB-AR (from V2.0.0)<br>(114903)         | Brief instructions for teach-in operation               | www      |
|   |   |          |



#### Important!

Always read all documents to gain a complete overview of safe installation, setup and use of the device. The documents can be downloaded from www.euchner.de. Enter the document number in the search box for this purpose.

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#### 2. Correct use

The system comprises at least one locking module MGB-L1-.../MGB-L2-... and one handle module MGB-H...

The safety system MGB is an interlocking device with guard locking (type 4). Devices with unicode evaluation possess a high coding level; devices with multicode evaluation feature a low coding level.

The locking module can be configured with the aid of DIP switches. Depending on the setting, the locking module behaves like an AP or AR device (see chapter 2.1. Main differences between MGB-AP and MGB-AR on page 7). In addition the guard lock monitoring can be switched on or off. More detailed information about the possible settings is available in the chapter 11.6. Changing device configuration (using DIP switches) on page 26.



#### With active guard lock monitoring the following applies:

In combination with a movable safety guard and the machine control, this safety component prevents the safety guard from being opened while a dangerous machine function is being performed.

This means:

- Starting commands that cause a dangerous machine function must become active only when the safety guard is closed and locked.
- The guard locking device must not be unlocked until the dangerous machine function has ended.
- Closing and locking a safety guard must not cause automatic starting of a dangerous machine function. A separate start command must be issued. For exceptions, refer to EN ISO 12100 or relevant C-standards.

#### With inactive guard lock monitoring the following applies:

In combination with a movable safety guard and the machine control, this safety component prevents dangerous machine functions from occurring while the safety guard is open. A stop command is triggered if the safety guard is opened during the dangerous machine function. With inactive guard lock monitoring, guard locking must be used only for process protection.

This means:

- Starting commands that cause a dangerous machine function must become active only when the safety guard is closed.
- Opening the safety guard triggers a stop command.
- Closing a safety guard must not cause automatic starting of a dangerous machine function. A separate start command must be issued. For exceptions, refer to EN ISO 12100 or relevant C-standards.

Before the device is used, a risk assessment must be performed on the machine, e.g. in accordance with the following standards:

- EN ISO 13849-1, Safety of machinery Safety-related parts of control systems Part 1: General principles for design
- EN ISO 12100, Safety of machinery General principles for design Risk assessment and risk reduction
- IEC 62061, Safety of machinery Functional safety of safety-related electrical, electronic and programmable electronic control systems

Correct use includes observing the relevant requirements for installation and operation, particularly based on the following standards:

- EN ISO 13849-1, Safety of machinery Safety-related parts of control systems Part 1: General principles for design
- EN ISO 14119 (supersedes EN 1088), Safety of machinery Interlocking devices associated with guards Principles for design and selection
- EN 60204-1, Safety of machinery Electrical equipment of machines Part 1: General requirements

The safety system MGB can only be combined with the intended modules in the MGB system family.

On the modification of system components, EUCHNER provides no warranty for function.



Locking modules with the configuration MGB-AR can be integrated into an AR switch chain.

Connection of several devices in an AR switch chain is permitted only using devices intended for series connection in an AR switch chain. Check the operating instructions for the related device.





#### Important!

- The user is responsible for the proper integration of the device into a safe overall system. For this purpose, the overall system must be validated, e.g. in accordance with EN ISO 13849-2.
- Correct use requires observing the permissible operating parameters (see chapter 13. Technical data on page 36).
- If a product data sheet is included with the product, the information on the data sheet applies.

#### Table 1: Possible combinations for MGB components

| Evaluation unit  MGBAR/AP from V3.0.0 |   | MGB-H from V2.0.0    |
|---------------------------------------|---|----------------------|
|                                       |   | •                    |
| Key to symbols                        | • | Combination possible |

### 2.1. Main differences between MGB-AP and MGB-AR

| System family | Symbol | Use  |
|---------------|--------|--|
| MGB-AP        | AP     | Optimized for operation in safe control systems.  If series connection is not necessary, the number of terminals can be reduced using this system family.                      |
| MGB-AR        | AR     | Linking of several safety guards on one shutdown path. As a consequence several safety doors can be very simply polled using one evaluation unit or two control system inputs. |

EN



## 3. Description of the safety function

Devices from this series feature the following safety functions:

#### With active guard lock monitoring the following applies:



## Monitoring of guard locking and the position of the safety guard (interlocking device with guard locking according to EN ISO 14119)

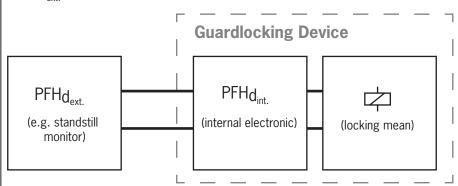
- Safety function (see chapter 6. Function on page 10):
  - The safety outputs are switched off when guard locking is unlocked (monitoring of the locking device). **Important:** This applies only if guard lock monitoring is active!
  - The safety outputs are switched off when the safety guard is open.
  - Guard locking can be activated only when the bolt tongue is located in the locking module (failsafe locking mechanism).
- Safety characteristics: category, Performance Level, PFH<sub>d</sub> (see chapter 13. Technical data on page 36).

#### Control of guard locking

Safety function.

If the device is used as guard locking for personnel protection, control of guard locking must be regarded as a safety function.

The safety level of guard locking control is determined by the device  $PFH_{d_{int.}}$  and by the external control (e.g.  $PFH_{d_{ext}}$  of the standstill monitor).



Safety characteristics: category, Performance Level, PFH<sub>d</sub> (see chapter 13. Technical data on page 36).

#### With inactive guard lock monitoring the following applies:



## Monitoring of the safety guard position (interlocking device according to EN ISO 14119)

- Safety function: The safety outputs are switched off when the safety guard is open (see chapter 6. Function on page 10).
- Safety characteristics: category, Performance Level, PFH<sub>d</sub> (see chapter 13. Technical data on page 36).

#### The following applies to devices with emergency stop:

## Emergency stop (emergency stop device according to EN ISO 13850)

- Safety function: emergency stop function
- ▶ Safety characteristics: B<sub>10d</sub> value (see chapter 13. Technical data on page 36)



## 4. Exclusion of liability and warranty

In case of failure to comply with the conditions for correct use stated above, or if the safety instructions are not followed, or if any servicing is not performed as required, liability will be excluded and the warranty void.

## 5. General safety instructions

Safety switches fulfill personal protection functions. Incorrect installation or tampering can lead to fatal injuries to personnel.

Check the safe function of the safety guard particularly

- ▶ after any setup work
- after the replacement of an MGB component
- after an extended period without use
- after every fault
- after any change to the DIP switch setting

Independent of these checks, the safe function of the safety guard should be checked at suitable intervals as part of the maintenance schedule.



#### WARNING

Danger to life due to improper installation or due to bypassing (tampering). Safety components perform a personal protection function.

- Safety components must not be bypassed, turned away, removed or otherwise rendered ineffective. On this topic pay attention in particular to the measures for reducing the possibility of bypassing according to EN ISO 14119:2013, section 7.
- The switching operation is only allowed to be triggered by the intended handle module MGB-H... that is positively fastened to the safety guard.
- Prevent bypassing by means of replacement actuators (only for multicode evaluation). For this purpose, restrict access to actuators and to keys for releases, for example.
- Mounting, electrical connection and setup only by authorized personnel possessing the following knowledge:
- specialist knowledge in handling safety components
- knowledge about the applicable EMC regulations
- knowledge about the applicable regulations on occupational safety and accident prevention.



#### Important!

Prior to use, read the operating instructions and keep these in a safe place. Ensure the operating instructions are always available during mounting, setup and servicing. EUCHNER cannot provide any warranty in relation to the readability of the CD for the storage period required. For this reason you should archive a printed copy of the operating instructions. You can download the operating instructions from www.euchner.de.

EN



## 6. Function

Together with a handle module, the locking module makes it possible to lock moving safety guards. The combination also serves as a mechanical door stop at the same time.



The following switch-on condition applies to the safety outputs FO1A and FO1B (also see chapters 14.2. MGB-AR system status table on page 38 and 14.3. MGB-AP system status table on page 39):

|           | Configuration System   | System family |        | B-AR       | MGB-AP            |            |
|-----------|--|---------------|--------|------------|-------------------|------------|
|           | Guard lock moni  | toring        | active | inactive   | active            | inactive   |
|           | No fault in the device   |               | TRUE   | TRUE       | TRUE              | TRUE       |
|           | Safety guard closed  |               | TRUE   | TRUE       | TRUE              | TRUE       |
| Ē         | Bolt tongue inserted in locking module   |               | TRUE   | TRUE       | TRUE              | TRUE       |
| Condition | Guard locking active   |               | TRUE   | irrelevant | TRUE              | irrelevant |
| Con       | In case of series connection: Signal available from the upstream switch on the safety inputs FI1A a FI1B In case of separate operation: DC 24 V present at the safety inputs FI1A and FI1B | nd            | TRUE   | TRUE       | irrelevant        | irrelevant |
|           |  |               |        | FO1A and F | 01B are <b>ON</b> |            |

The locking module detects the position of the safety guard and the position of the bolt tongue. The position of the guard locking is also monitored.

Guard lock monitoring can be deactivated using DIP switches (see chapter 11.6. Changing device configuration (using DIP switches) on page 26).



#### Important!

For use as guard locking in accordance with EN ISO 14119, guard lock monitoring must be active.

The bolt tongue in the handle module is moved into and out of the locking module by actuating the door handle.

When the bolt tongue is fully inserted in the locking module, the locking arm locks the bolt tongue in this position. Depending on the version, this locking is by spring force or solenoid force.

#### 6.1. Guard locking for version MGB-L1

(guard locking actuated by spring force and released by energy ON)

**Activating guard locking:** close safety guard; no voltage at the solenoid.

Releasing guard locking: apply voltage to the solenoid.

The spring-operated guard locking functions in accordance with the closed-circuit current principle. If voltage is interrupted at the solenoid, guard locking remains active and the safety guard cannot be opened directly.



#### Important!

If the safety guard is open when the power supply is interrupted and the guard is then closed, guard locking is activated. This can lead to persons being locked in unintentionally.

As long as the locking arm is closed, the bolt tongue cannot be pulled out of the locking module and the safety guard is locked.

When voltage is applied to the locking solenoid, the locking arm is opened and bolt tongue is released. The safety guard can be opened.



## 6.2. Guard locking for version MGB-L2

(guard locking actuated by energy ON and released by spring force)



#### Important!

Use as guard locking for personnel protection is possible only in special cases, after strict assessment of the accident risk (see EN ISO 14119:2013, section 5.7.1)!

**Activating guard locking:** apply voltage to the solenoid.

**Releasing guard locking:** disconnect voltage from the solenoid.

The magnetically actuated guard locking operates in accordance with the open-circuit current principle. If voltage is interrupted at the solenoid, guard locking is released and the safety guard can be opened directly!

The safety guard can be opened as long as no voltage is applied to the guard locking solenoid.

When voltage is present at the guard locking solenoid, the the locking arm is held in locked position and the safety guard is locked.

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## 7. System overview

## 7.1. Locking module MGB-L.-...

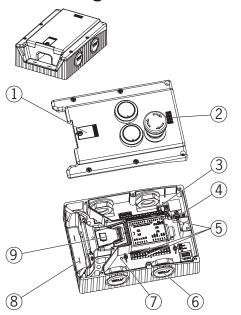


Figure 1: Locking module MGB-L.-...

#### Key:

- Cover for mechanical release
- 1 2 LED indicator
- 3 4 Jumper
- DIP switches Terminals X2-X5
- <u>5</u> 6 Depending on version
  - Cable entry M20x1.5 or plug connector
- (7)
- (8) Auxiliary marking for maximum permitted mounting distance
- 9 Locking arm

Depending on the version, additional controls and indicators may be integrated into the cover and a mounting plate can be included.

See enclosed data sheet.

### 7.2. Handle module MGB-H-...

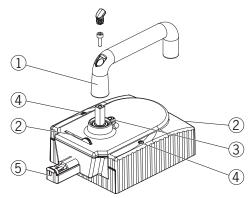


Figure 2: Handle module MGB-H-...

## Key:

- ① Door handle
- Fold-out lockout mechanism (optional: second, automatically extending lockout mechanism)
- Locking pin for handle adjustment
- Locking screws T10 for housing cover
- 6 Bolt tongue

#### Notice:

Depending on the version, a mounting plate can be included. See enclosed data sheet.

## 7.3. Escape release MGB-E-... (optional)

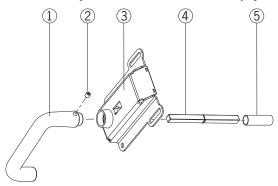


Figure 3: Escape release MGB-E-...

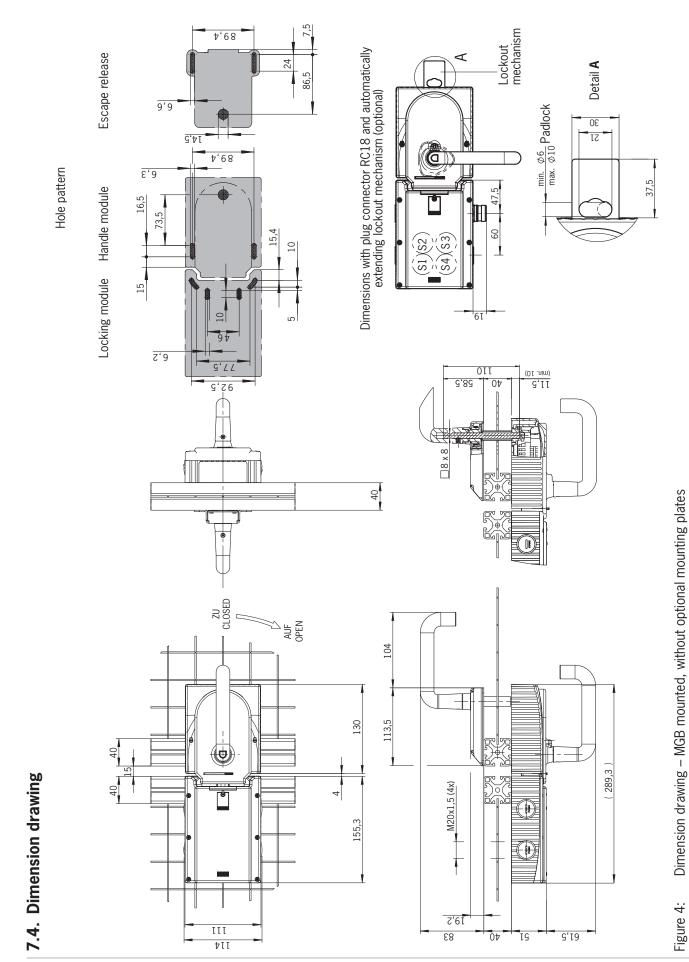
#### Key:

- Door handle
- Setscrew
- Cover
- Actuation axis 8 x 8 mm (different lengths available)
- Protective sleeve

#### Notice:

Depending on the version, a mounting plate can be included. See enclosed data sheet.

ΕN



119167-03-01/15 (translation of the original operating instructions)

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#### 7.5. Manual release

Some situations require guard locking to be released manually (e.g. malfunctions or an emergency). A function test should be performed after release.

More information on this topic can be found in the standard EN ISO 14119:2013, section 5.7.5.1. The device can feature the following release functions:

#### 7.6. Mechanical release

In the event of service, the guard locking can be released with the mechanical release irrespective of the state of the solenoid (see *Figure 5*).



- When release monitoring is active, the system enters into a latching fault when the mechanical release is actuated. See *System status table*, *signal sequence incorrect* status (DIA red, Lock flashes 1 time).
- The system might not enter into a latching fault if the mechanical release is actuated very slowly.



#### Important!

- The mechanical release is not a safety function.
- The machine manufacturer must select and use a suitable release (escape release, emergency unlocking, etc.) for a specific application. A risk assessment is required for this purpose. It may be necessary to take specifications from a product standard into account.
- The correct function must be checked at regular intervals.
- Loss of the release function due to mounting errors or damage during mounting. Check the release function every time after mounting.
- Please observe the notes on any enclosed data sheets.

The locking screw must be screwed back in and sealed (for example with sealing lacquer) after assembly and after every use of the mechanical release. Tightening torque 0.5 Nm.

- 1. Undo locking screw.
- 2. Lift locking arm using a screwdriver and actuate door handle.

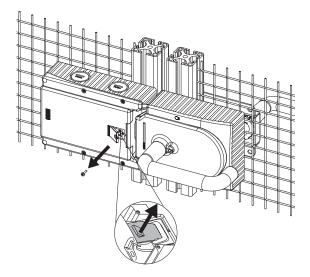


Figure 5: Mechanical release



## 7.7. Emergency unlocking (can be retrofitted)

Permits opening of a locked safety guard from outside the danger area without tools. For mounting, see the mounting supplement.



#### Important!

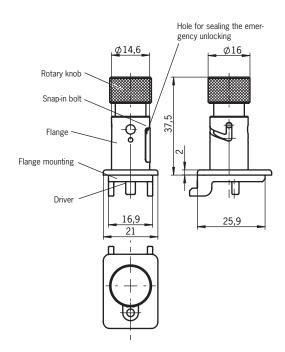
- It must be possible to operate emergency unlocking manually from outside the protected area without tools.
- Emergency unlocking must possess a marking indicating that it may be used only in an emergency.
- The actuator must not be under tensile stress during manual release.
- The unlocking function meets all other requirements from EN ISO 14119.
- Emergency unlocking meets the requirements of Category B according to EN ISO 13849-1:2008.
- Loss of the unlocking function due to mounting errors or damage during mounting.
- ▶ Check the release function every time after mounting.
- Please observe the notes on any enclosed data sheets.

#### 7.7.1. Actuating emergency unlocking

- Press emergency unlocking and turn clockwise by 90° until it clicks into place.
- Guard locking is released.

To reset, press the snap-in bolt inward using a small screwdriver or similar tool and turn the emergency unlocking back. The emergency unlocking can be sealed in free position.

The safety outputs  $\blacksquare$  are switched off when emergency unlocking is actuated. Use the safety outputs  $\blacksquare$  to generate a stop command.



#### 7.8. Lockout mechanism

If the lockout mechanism is pivoted out/extended, the bolt tongue cannot be extended. The lockout mechanism can be secured with padlocks (see *Figure 6*).

→ To pivot out, press the grooved part (only possible with bolt tongue retracted).

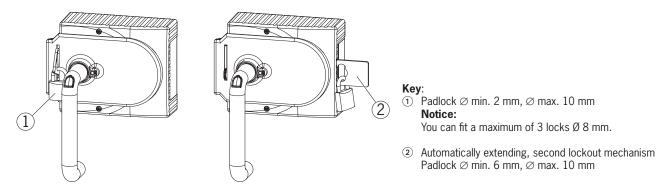


Figure 6: Lockout mechanism secured with padlock

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## 7.9. Escape release (optional)

The escape release is used to open a locked safety guard from the inside without tools.



When release monitoring is active, the system enters into a latching fault when the escape release is actuated. See *System status table*, *signal sequence incorrect* status (DIA red, Lock flashes 1 time). The system might not enter into a latching fault if the escape release is actuated very slowly.



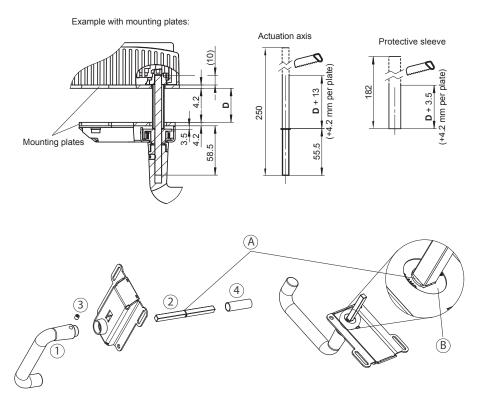
#### Important!

- It must be possible to operate the escape release manually from inside the protected area without tools.
- It must not be possible to reach the escape release from the outside.
- The actuator must not be under tensile stress during manual release.
- The escape release meets the requirements of Category B according to EN ISO 13849-1:2008.
- Fit escape release such that operation, inspection and service are possible.
- The actuation axis for the escape release must be inserted min. 10 mm into the handle module. Note the information on the different profile widths in the next chapter.
- Align escape release axis at right angles to the handle module. See Figure 4 and Figure 8.

#### 7.9.1. Preparing escape release

(also see Figure 7: Preparing escape release on page 17)

| Profile width | Length required for actuation axis |                                  | Which EUCHNER parts are required?   | Necessary work steps   |  |
|---------------|------------------------------------|----------------------------------|---|--|--|
|               | Without plates                     | With mounting plates (4 mm each) |   |  |  |
| D             | D+13                               | D+21                             |   |  |  |
| 30 mm         | 43 mm                              | 51 mm                            | Standard escape release with 110 mm axis (order no. 100465)   | Shorten to required length   |  |
| 40 mm         | 53 mm                              | 61 mm                            | Standard escape release<br>with 110 mm axis<br>(order no. 100465)<br>If necessary<br>extended actuation axis (order no. 106761) | Without mounting plates: None With mounting plates: Use long actuation axis and protective sleeve and shorten to required length |  |
| 45 mm         | 58 mm                              | 66 mm                            | Standard escape release with 110 mm axis (order no. 100465) and extended actuation axis (order no. 106761)                      | Use long actuation axis and protective sleeve and shorten to required length   |  |
| 50 mm         | 63 mm                              | 71 mm                            | Standard escape release with 110 mm axis (order no. 100465) and extended actuation axis (order no. 106761)                      | Use long actuation axis and protective sleeve and shorten to required length   |  |



- Fit door handle.
- Insert actuation axis. The locking ring  ${\bf A}$  must be in contact with the escape release  ${\bf B}$ .
- ① ② ③ Tighten setscrew to 2 Nm.
- Fit protective sleeve.

Figure 7: Preparing escape release



## 8. Mounting



#### **WARNING**

Mounting must be performed only by authorized personnel.

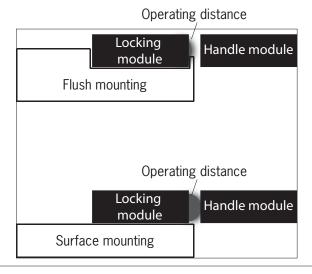
With two-wing hinged doors, one of the two door wings additionally must be latched mechanically.

Use a rod latch (Item) or a double-door lock (Bosch Rexroth) for this purpose, for example.



#### Important!

If installed flush, the switching distance changes as a function of the installation depth and the safety guard material.





#### Tip!

- You will find an animation on the mounting process at www.euchner.de.
- The color and labeling of pushbuttons and indicators can be modified.

For mounting steps, see Figure 8 and Figure 9 to Figure 14.

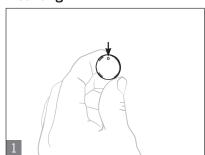
Attach system such that operation of the mechanical release as well as inspection and maintenance are possible.

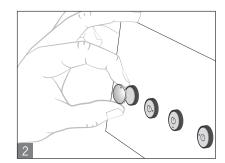
The locking screw of the escape release must be returned to its original position and sealed before putting into operation (for example with sealing lacquer).

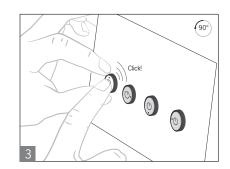


## 8.1. Mounting color cover

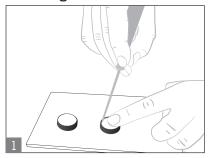
## Mounting

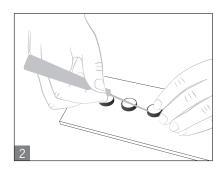






### Removing









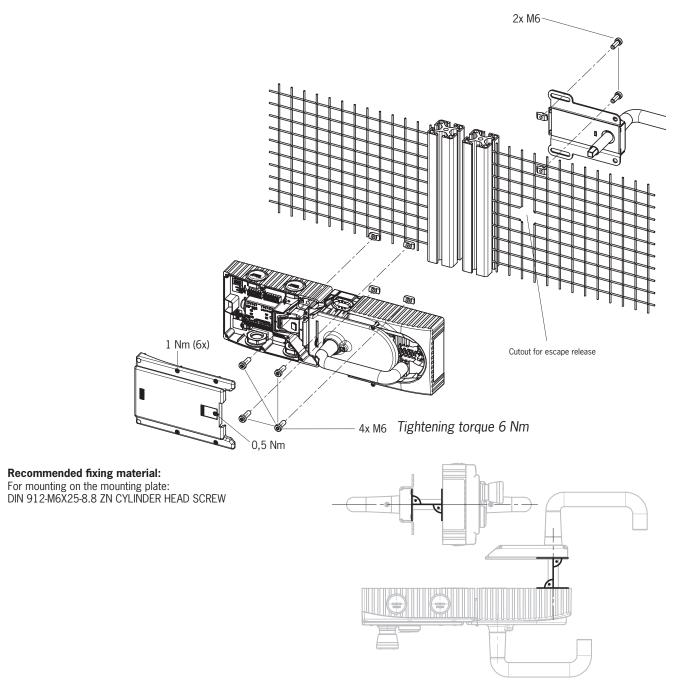


Figure 8: Installation example for door hinged on the right (general view)

## 9. Changing actuating direction (here: from right to left)



#### Important!

It is only possible to make this change when the bolt tongue is not extended and an escape release is not yet mounted.

As supplied, the handle module is set either for doors hinged on the right or for doors hinged on the left.

Based on the example of a handle module for doors hinged on the right this means:

- The safety guard opens by pressing down the door handle.
- The system is mounted the other way around for doors hinged on the left. In other words, the safety door opens by pressing up the door handle (see *Figure 9*). For this reason the actuating direction of the door handle must be changed (see *Figure 9* to *Figure 14*).

(similarly on handle modules for doors hinged on the left)

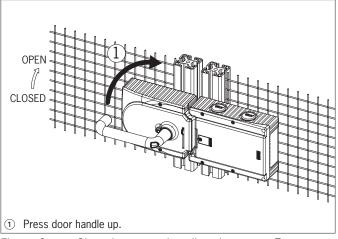


Figure 9: Changing actuating direction, step 1

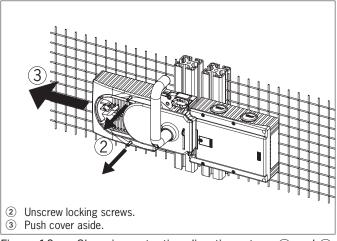


Figure 10: Changing actuating direction, steps 2 and 3

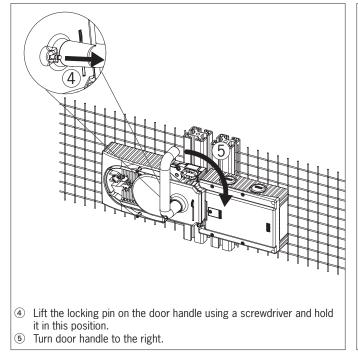
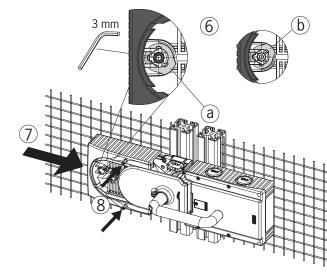


Figure 11: Changing actuating direction, steps 4 and 5

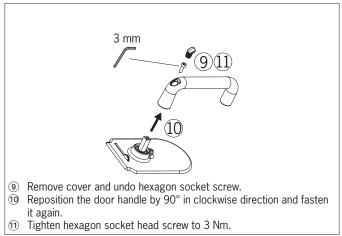


- 6 Only if using an escape release: using the hexagon head screw, turn the joint counterclockwise from position (a) to position (b).
- Close cover.
- 8 Screw in locking screws and tighten to 0.8 Nm.

Figure 12: Changing actuating direction, steps 6 to 8

EN





CLOSED
OPEN

3 State after repositioning.

Figure 13: Changing actuating direction, steps (9) and (1)

Figure 14: Changing actuating direction, final state

## 10. Protection against environmental effects

Lasting and correct safety function requires that the system must be protected against foreign bodies such as swarf, sand, blasting shot, etc., which can become lodged in the locking and handle modules. For this purpose a suitable installation position should be selected.

Cover device during painting work!



## 11. Electrical connection



#### **WARNING**

In case of an error, loss of the safety function through incorrect connection.

- To ensure safety, both safety outputs (FO1A and FO1B) must always be evaluated.
- The monitoring outputs must not be used as safety outputs.
- Lay the connection cables with protection to prevent the risk of short circuits.



#### **CAUTION**

Risk of damage to equipment or malfunctions as a result of incorrect connection.

- The inputs on an evaluation unit connected must be positive-switching, as the two outputs on the safety switch deliver a level of +24 V in the switched-on state.
- All the electrical connections must either be isolated from the mains supply by a safety transformer according EN IEC 61558-2-6 with limited output voltage in the event of a fault, or by other equivalent isolation measures.
- All electrical outputs must have an adequate protective circuit for inductive loads. The outputs must be protected with a free-wheeling diode for this purpose. RC interference suppression units must not be used.
- Power devices which are a powerful source of interference must be installed in a separate location away from the input and output circuits for signal processing. The cable routing for safety circuits should be as far away as possible from the cables of the power circuits.
- To prevent EMC problems, it is imperative you follow the chapter 11.5. Notes on cable laying on page 25. Follow EMC notes on devices in the immediate vicinity of the MGB system and their cables.
- In order to avoid EMC interference, the physical environmental and operating conditions at the installation site of the device must comply with the requirements according to the standard DIN EN 60204-1:2006, section 4.4.2/EMC.



#### Important!

- If the device does not appear to function when the operating voltage is applied (e.g. green Power LED does not illuminate), the safety switch must be returned to the manufacturer.
- To ensure the stated degree of protection is achieved, the cover screws must be tightened to a tightening torque of 1 Nm.
- Tighten screw for the cover for the mechanical release to 0.5 Nm.

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## 11.1. Notes about ((1) us



#### Important!

- For use and operation as per the • requirements 1), a power supply with the feature "for use in class 2 circuits" must be used. The same requirement applies to the safety outputs.

  Alternative solutions must comply with the following requirements:
  - a) Electrically isolated power supply unit with a max. open-circuit voltage of 30 V/DC and a limited current of max. 8 A.
  - b) Electrically isolated power supply unit in combination with fuse as per UL248. This fuse should be designed for max. 3.3 A and should be integrated into the 30 V DC voltage section.
- The mounting of conduits directly on the MGB is not allowed. Cables are only allowed to be connected via suitable cable glands. For this purpose use EUCHNER cable gland of type EKP-M20/06U. Equivalent cable glands can be used if they are UL-listed (QCRV) and are suitable for the related cable diameter (22 AWG 17 AWG).

## 11.2. Safety in case of faults

- The operating voltage UB is reverse polarity protected.
- ▶ The safety outputs FO1A/FO1B are short circuit-proof.
- A short circuit between FI1A and FI1B or FO1A and FO1B is detected by the device.
- A short circuit in the cable can be excluded by laying the cable with protection.

## 11.3. Fuse protection for power supply

The power supply must be provided with fuse protection depending on the number of devices and current required for the outputs. The following rules apply:

#### Max. current consumption of an individual device Imax

 $I_{\text{max}} = I_{\text{UB}} + I_{\text{UA}} + I_{\text{FO1A+FO1B}}$ 

 $I_{UB}$  = Device operating current (80 mA)

 $I_{UA}$  = Load current of monitoring outputs OD, OT, OL and OI (4 x max. 50 mA) + solenoid + switches

 $I_{FO1A+FO1B}$  = Load current of safety outputs FO1A + FO1B (2 x max. 200 mA)



## Max. current consumption of a switch chain $\Sigma$ I<sub>max</sub>

 $\Sigma I_{\text{max}} = I_{\text{FO1A+FO1B}} + n \times (I_{\text{UB}} + I_{\text{UA}})$ 

n = Number of connected devices

#### **Current assignment to the fuses**

| Current                 | Fuse circuit F1   | Fuse circuit F2                                       |  |
|-------------------------|-------------------|---|--|
| $I_{UB}$                | 80 mA             |   |  |
| I <sub>F01A+</sub> F01B | (2 x max. 200 mA) |   |  |
|                         |                   | I <sub>solenoid</sub> = 375 mA                        |  |
|                         |                   | $I_{OD,OT,OL,OI} = (4 \text{ x max. } 50 \text{ mA})$ |  |
| 1                       |                   | I <sub>switches</sub> = max. 100 mA                   |  |
| IUA                     |                   | (per switch)  |  |
|                         |                   | l <sub>indicators</sub> = max. 5 mA                   |  |
|                         |                   | (per indicator)                                       |  |

Note on the scope of the UL approval: Only for applications as per NFPA 79 (Industrial Machinery).
 The devices have been tested as per the requirements of UL508 (protection against electric shock and fire).



## 11.4. Requirements for connection cables



#### **CAUTION**

Risk of damage to equipment or malfunctions as a result of incorrect connection cables.

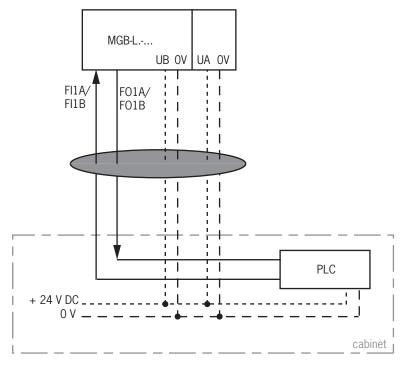
• On the usage of other connection components, the requirements in the following table apply. EUCHNER provides no warranty for safe function in case of failure to comply with these requirements.

Observe the following requirements with respect to the connection cables:

| Parameter                    | Value | Unit  |
|------------------------------|-------|-------|
| Conductor cross-section min. | 0.13  | mm²   |
| R max.                       | 60    | Ω/κμ  |
| C max.                       | 120   | nF/km |
| L max.                       | 0.65  | mH/km |

## 11.5. Notes on cable laying

Lay all MGB connection cables in a common cable harness.



Important: lay cables in a common harness

Figure 15: Stipulated cable laying

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## 11.6. Changing device configuration (using DIP switches)



#### Tip!

You will find an animation on device configuration at www.euchner.de.

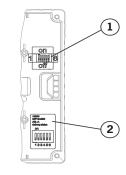
#### **DIP** switches

The devices can be configured using the DIP switches. The following settings are possible:

- Changing system family (AR/AP switching)
- Deactivating guard lock monitoring
- Activating release monitoring (possible only with active guard lock monitoring)

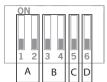
#### Position of the switches

| Item | Description                  |
|------|------------------------------|
| 1    | DIP switches                 |
| 2    | Sticker with factory setting |



#### **Function of the switches**

| Detail | Switch | Function   |
|--------|--------|--|
| А      | 1+2    | on: Device is operated as AP system                              |
|        |        | off: Device is operated as AR system                             |
| В      | 3+4    | on: Guard lock monitoring is deactivated                         |
|        |        | off: Guard lock monitoring is active (usually factory setting)   |
| С      | 5      | on: Configuration possible                                       |
|        |        | off: Configuration inhibited (factory setting)                   |
| D      | 6      | on: Release monitoring is activated                              |
|        |        | off: Release monitoring is deactivated (usually factory setting) |



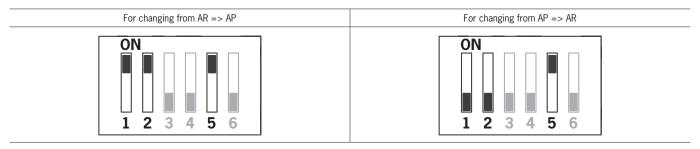
#### 11.6.1. Changing system family (AR/AP switching)



#### **CAUTION**

Malfunction due to incorrect configuration or incorrect connection.

- Note that the terminal assignment also changes on changing the configuration (see chapter 11.9. Terminal assignment and contact description on page 30).
- 1. Switch off power supply.
- 2. Set DIP switches 1, 2 and 5 as shown.



- 3. Switch on power supply for 5 s.
- → The change is confirmed by the illumination of the Power LED. All other LEDs are off.
- 4. Switch off power supply and set DIP switch 5 to OFF.
- → The next time the device is started, it operates in the operating mode set.



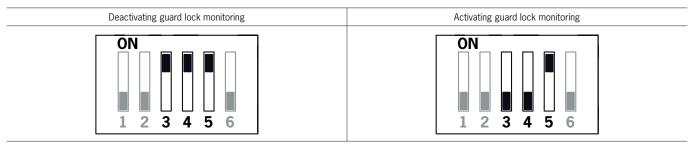
#### 11.6.2. Deactivating guard lock monitoring



#### **WARNING**

Risk of injury due to inactive guard lock monitoring.

- When guard lock monitoring is inactive, the guard locking position does not influence the safety outputs. The safety guard can be opened immediately. This setting is not allowed to be used in applications in which, e.g., there is hazard due to overrunning machinery movement. With inactive guard lock monitoring, guard locking must be used only for process protection.
- 1. Switch off power supply.
- 2. Set DIP switches 3-5 as shown.



- 3. Switch on power supply for 5 s.
- → The change is confirmed by the illumination of the Power LED. All other LEDs are off.
- 4. Switch off power supply and set DIP switch 5 to OFF.
- → The next time the device is started, it operates in the operating mode set.

#### 11.6.3. Activating release monitoring



#### Important!

Release monitoring can be activated only if guard lock monitoring is also active.



### **NOTICE**

When release monitoring is active, the system enters into a latching fault when the escape release or mechanical release is actuated.

See System status table, signal sequence incorrect status (DIA red, Lock flashes 1 time).

- 1. Switch off power supply.
- 2. Set DIP switches 5 and 6 as shown.



- 3. Switch on power supply for 5 s.
- → The change is confirmed by the illumination of the Power LED. All other LEDs are off.
- 4. Switch off power supply and set DIP switch 5 to OFF.
- → The next time the device is started, it operates in the operating mode set.

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## 11.7. Notes on operation with control systems

Please observe the following requirements for connection to safe control systems:

#### **General notes**

- Use a common power supply for the control system and the connected safety switches.
- A pulsed power supply must not be used for UB/UA. Tap the supply voltage directly from the power supply unit. If the supply voltage is connected to a terminal of a safe control system, this output must provide sufficient electrical current.
- The safety outputs (F01A and F01B) can be connected to the safe inputs of a control system. Prerequisite: The input must be suitable for pulsed safety signals (OSSD signals, e.g. from light curtains). The control system must tolerate test pulses on the input signals. This normally can be set up by parameter assignment in the control system. Observe the notes of the control system manufacturer. For the pulse duration of your safety switch, please refer to the chapter 13. Technical data on page 36.
- The inputs on an evaluation unit connected must be positive-switching, as the two outputs on the safety switch deliver a level of +24 V in the switched-on state.



Always connect inputs FI1A and FI1B directly to a power supply unit or to outputs FO1A and FO1B of another EUCHNER AR device (series connection). Pulsed signals must not be present at inputs FI1A and FI1B. The test pulses are also present when the safety outputs are switched off (only on FO1A). Depending on the inertia of the connected device (control system, relay, etc.), this can lead to short switching processes.

#### **Guard locking control**

Test pulses up to max. 5 ms in duration at intervals of min. 100 ms are tolerated on IMP1, IMP2 and IMM.

The inputs on an evaluation unit connected must be positive-switching, as the two outputs on the safety switch deliver a level of +24 V in the switched-on state.



#### NOTICE

Due to the fact that short circuit monitoring of the safety outputs FO1A/FO1B is performed by the device itself, the Performance Level in accordance with EN 13849 is not reduced if the control system pulsing is switched off.



#### Tip!

A detailed example of connecting and setting the parameters of the control system is available for many devices at www.euchner.de in the area Download \* Applications \* MGB. The features of the respective device are dealt with there in greater detail.



## 11.8. Connection of guard locking control

1-channel control
1 x p-switching
2 x p-switching
1 x p-switching
1 x n-switching
1 x n-switching
1 x n-switching
1 x n-switching
1 mgp
1

Figure 16: Connection option for guard locking control

With 2-channel control, the jumper between IMP1 and IMP2 must be removed. Connection as shown above. Further adaptations may be required for some device versions with plug connector M23 (RC18) (see data sheet).

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## 11.9. Terminal assignment and contact description

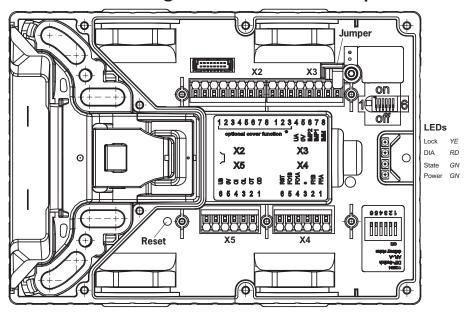


Figure 17: Connections and indicator LED

| Terminal     | Designation | Description   |  |  |  |  |  |  |
|--------------|-------------|---|--|--|--|--|--|--|
| X3.1 to X3.3 | -           | See the enclosed data sheet   |  |  |  |  |  |  |
| X3.4         | UA          | Power supply for the guard locking solenoid, monitoring outputs and cover the guard locking solenoid functions.   | er assembly, DC 24 V, must be present continuously so that |  |  |  |  |  |
| X3.5         | OV          | Ground, DC 0 V (connected internally to X5.5).  |  |  |  |  |  |  |
| X3.6         | IMP2        | (see chapter 11.8. Connection of guard locking control on page 29).   |  |  |  |  |  |  |
| X3.7         | IMP1        | Control voltage for switching the guard locking on and off, DC 24 V (see chapter 11.8. Connection of guard locking control on page 29).   | setting on delivery  |  |  |  |  |  |
| X3.8         | IMM         | Control voltage for switching the guard locking on and off, 0 V (see chapter 11.8. Connection of guard locking control on page 29).   |  |  |  |  |  |  |
| X4.1         | FI1A        | In case of AR configuration: Enable input for channel A, connect to DC nect output signal FO1A from previous device.  In case of AP configuration: Input is not evaluated.  | 24 V in separate operation. In case of switch chains, con- |  |  |  |  |  |
| X4.2         | FI1B        | In case of AR configuration: Enable input for channel B, connect to DC nect output signal F01B from previous device.  In case of AP configuration: Input is not evaluated.  | 24 V in separate operation. In case of switch chains, con- |  |  |  |  |  |
| X4.3         | -           | See the enclosed data sheet   |  |  |  |  |  |  |
| X4.4         | FO1A        | Safety output channel A (function dependent on DIP switch setting) <b>Guard lock monitoring active:</b> ON when door is closed and locked <b>Guard lock monitoring inactive:</b> ON when door is closed and bolt tong |  |  |  |  |  |  |
| X4.5         | FO1B        | Safety output channel B (function dependent on DIP switch setting) <b>Guard lock monitoring active:</b> ON when door is closed and locked <b>Guard lock monitoring inactive:</b> ON when door is closed and bolt tong |  |  |  |  |  |  |
| X4.6         | RST         | Reset input, device is reset if DC 24 V is applied to RST for at least 3 s.   |  |  |  |  |  |  |
| X5.1         | OD          | Door monitoring output,<br>ON when the door is closed.  |  |  |  |  |  |  |
| X5.2         | OT          | Bolt tongue monitoring output,<br>ON when the door is closed and the bolt tongue is inserted in the locking   | module.  |  |  |  |  |  |
| X5.3         | OL          | Guard locking monitoring output,<br>ON when the door is closed and locked   |  |  |  |  |  |  |
| X5.4         | Ol          | Diagnostics monitoring output,<br>ON when the device is in the fault state.   |  |  |  |  |  |  |
| X5.5         | OV          | Ground, DC 0 V (connected internally to X3.5).  |  |  |  |  |  |  |
| X5.6         | UB          | Power supply, DC 24 V   |  |  |  |  |  |  |
| X2.1 to X2.8 | -           | See the enclosed data sheet   |  |  |  |  |  |  |
| X1           | -           | Reserved for connection of the cover circuit board (only for populated co   | vers)  |  |  |  |  |  |

Table 2: Terminal assignment and contact description



## 11.10. Operation as separate device

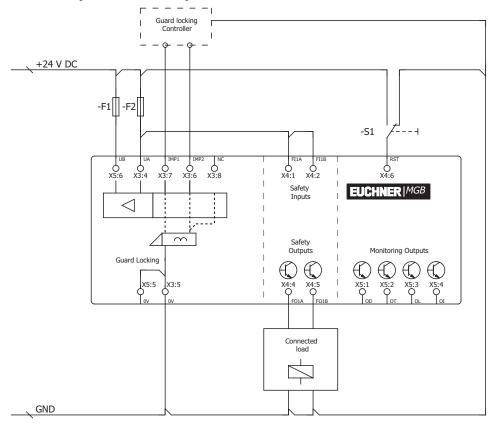


Figure 18: Connection example for separate operation

The switches can be reset via the RST input. To do this, a voltage of 24 V is applied to the RST input for at least 3 seconds. The supply voltage to the switches is interrupted during this time. The RST input must be connected to 0 V if it is not used.

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## 11.11. Operation in an AR switch chain

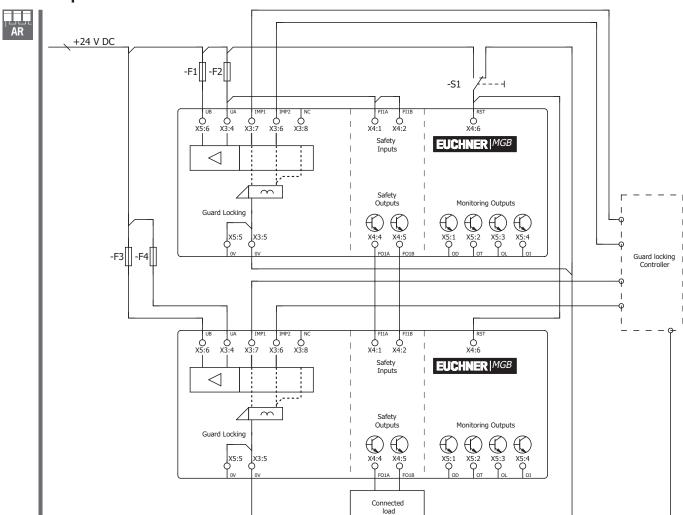


Figure 19: Connection examples for operation in a CES-AR switch chain

For detailed information on operation in an AR switch chain, see the related CES-AR operating instructions. The locking module MGB-L1-AR-.../MGB-L2-AR-... behaves in the switch chain in practice like a safety switch CES-AR. The differences to the CES-AR are described in the following.

**GND** 



## 11.12. Notes on operation in an AR switch chain

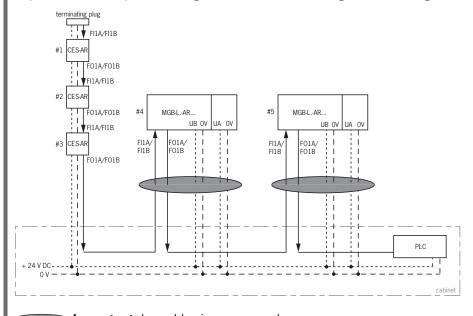


#### 11.12.1. System times

The locking module has longer reaction times than a CES-AR switch (see chapters 13. Technical data on page 36 and 13.1. Typical system times on page 37).

#### 11.12.2. Wiring an AR switch chain

To prevent earth loops, the wiring should be in a star configuration (see Figure 20).



Important: lay cables in a common harness

Figure 20: Central wiring of an AR switch chain in the control cabinet

#### 11.12.3. Number of devices in the switch chains

In a pure MGB switch chain a maximum of ten devices can be connected in series. In mixed switch chains (e.g. MGB together with CES-AR) the maximum number of devices is also ten.

#### 11.12.4. Resetting in switch chains



#### Important!

Use the reset input (RST) for resetting in AR switch chains. All devices in the chain must be reset simultaneously. Resetting individual switches will result in faults.

ΕN



## 12. Setup

## 12.1. Teach-in operation (only for MGB unicode)

The handle module must be assigned to the locking module using a teach-in function before the system comprising locking module and handle module and forms a functional unit.

During a teach-in operation the safety outputs are switched off.



#### Important!

- The locking module disables the code for the previous handle module if teach-in is carried out for a new handle module. Teach-in is not possible again immediately for this actuator if a new teach-in operation is carried out. The disabled code is deleted in the locking module only after a third code has been taught.
- The locking module can only be operated with the last handle module taught.
- If, in the teach-in standby state, the locking module detects the handle module taught-in or a disabled handle module, the teach-in standby state is ended immediately and the locking module changes to the normal state.
- If the bolt tongue is in the operating distance for less than 60 s, the handle module is not taught.



#### Tip!

A teach-in adapter (order no. 122369) is available for easier teach-in of already mounted AR devices or for device replacement. It is simply inserted between the connecting cable and the AR device. The device immediately enters teach-in operation on reconnection. After teach-in, the adapter is removed again and the MGB is connected normally. It is not necessary to fit a jumper (e.g. in the control cabinet).

#### Teaching in handle module

- 1. Fit handle module.
- 2. Close safety guard. Check for correct alignment and distance using the marking on the locking module and re-adjust if necessary.
- 3. Insert bolt tongue in the locking module.
- 4. Apply operating voltage to the locking module.
- → The green LED (State) flashes quickly (approx. 5 Hz). A self-test is performed during this time (approx. 10 s in case of AR configuration). Teach-in operation starts, green LED (State) flashes slowly (approx. 1 Hz). During teach-in, the locking module checks whether the handle module is a disabled handle module. Provided this is not the case, the teach-in operation is completed after approx. 60 seconds, and the green LED (State) goes out. The new code has now been stored, and the old code is disabled.
- 5. To activate the handle module's code from the teach-in operation in the locking module, the operating voltage must then be switched off at the locking module for min. 3 seconds. As an alternative, 24V can be applied to the input RST for min. 3 seconds.

Teach-in in a series connection works analogously. Here, the complete series connection must be restarted using the input RST.

#### 12.2. Mechanical function test

It must be possible to easily insert the bolt tongue in the locking module. To check, close safety guard several times and actuate door handle.

If available, check function of the escape release. With active guard locking it must be possible to operate the escape release from the inside without excessive effort (approx. 40 N).



#### **Electrical function test**





#### **WARNING**

On usage in a switch chain with different AR devices (e.g. CES-AR, CET-AR), also follow the procedure for the functional check in the related operating instructions.



#### With active guard lock monitoring

- 1. Switch on operating voltage.
- → The locking module carries out a self-test. In case of AR configuration: The green State LED flashes for 10 s with 5 Hz. The green State LED then flashes at regular intervals.
- 2. Close all safety guards and insert the bolt tongue into the locking module. Guard locking by solenoid force: activate guard locking.
- → The safety outputs FO1A/FO1B → are ON.
- The machine must not start automatically.
- → It must not be possible to open the safety guard.
- → The green State LED and the yellow Lock LED are illuminated continuously.
- 3. Enable operation in the control system.
- ▶ It must not be possible to deactivate guard locking as long as operation is enabled.
- 4. Disable operation in the control system and deactivate guard locking.
- → The safety guard must remain locked until there is no longer any risk of injury.
- → It must not be possible to start the machine as long as the guard locking is deactivated.
- → It must be possible to open the safety guard.

Repeat steps 2-4 for each safety guard.

#### With inactive guard lock monitoring

- 1. Switch on operating voltage.
- → The locking module carries out a self-test. In case of AR configuration: The green State LED flashes for 10 s with 5 Hz. The green State LED then flashes at regular intervals.
- 2. Close all safety guards and insert the bolt tongue into the locking module. As soon as the bolt tongue is inserted in the locking module, the safety outputs FO1A/FO1B are ON. Independent of whether the guard locking is active or not.
- → The machine must not start automatically.
- → The green State LED illuminates continuously. The yellow Lock LED is ON for a long time with a short interruption or is ON continuously (depending on the state of the guard locking).
- 3. Enable operation in the control system.
- 4. If necessary deactivate guard locking and open safety guard.
- → The machine must switch off and it must not be possible to start it as long as the safety guard is open.

Repeat steps 2-4 for each safety guard.

ΕN



## 13. Technical data



#### NOTICE

If a product data sheet is included with the product, the information on the data sheet applies in case of discrepancies with the operating instructions.

| Parameter  | Valu   | e  | Unit            |
|--|--|--|-----------------|
| Housing material   | Glass fiber reinfo                             | prced plastic;                           |                 |
|  | die-cast zinc, n                               | ickel-plated;                            |                 |
|  | stainless                                      | steel                                    |                 |
| Dimensions   | See chapter 7.4. Dimensi                       | on drawing on page 13                    |                 |
| Weight   | •  | 0 , 0                                    |                 |
| Locking module   | 0.75   |  |                 |
| Handle module  | 1.00   |  | kg              |
| Escape release   | 0.50   |  |                 |
| Ambient temperature at U <sub>B</sub> = DC 24 V  | -20  |  | °C              |
| Degree of protection   | 20   | 100                                      |                 |
| Cover not populated/populated with buttons/indi-   |  |  |                 |
| cators/selector switches   | IP 6   | 5  |                 |
| Cover populated with key-operated rotary switch  | IP 5   |  |                 |
| Cover populated with key-operated rotary switch FS22   | IP 4:  |  |                 |
| Safety class   |  |  |                 |
| Degree of contamination  | 3  |  |                 |
|  |  |  |                 |
| nstallation position   | Any  |  | N.              |
| ocking force F <sub>zh</sub> acc. to EN ISO 14119  | 2,00   | -  | N               |
| Connection   | 4 cable entries M20x1.                         |  |                 |
| Conductor cross-section (rigid/flexible)   | 0.13 1.5 (AWG                                  |  |                 |
| With ferrule according to DIN 46228/1  | 0.25   |  | mm <sup>2</sup> |
| With ferrule with collar according to DIN 46228/1  | 0.25   | 0./5                                     |                 |
| Operating voltage UB (reverse polarity protected,  | 24 +10% / -1                                   | 5% (PFLV)                                | V DC            |
| egulated, residual ripple < 5%)  | 24 +10/0/ -1                                   | 5/0 (I EEV)                              | V DC            |
| Auxiliary voltage UA (reverse polarity protected,  | 24 +10% / -1                                   | 50/ (DELV)                               | V DC            |
| regulated, residual ripple < 5%)   | 24 +10/6 / -1                                  | 3% (FLLV)                                | V DC            |
| Current consumption I <sub>UB</sub> (no load on any outputs)   | 80   |  | mA              |
| Current consumption I <sub>IIA</sub>   |  |  |                 |
| With energized guard locking solenoid and  |  |  | m 1             |
| unloaded outputs (OI, OL, OT and OD)   | 375  | j  | mA              |
| Push button S (unloaded, per LED)  | 5  |  |                 |
| External fuse  | See chapter 11.3. Fuse protection              | n for power supply on page 24            |                 |
| Safety outputs F01A/F01B   | Semiconductor outputs, p-sw                    | itching, short circuit-proof             |                 |
| Test pulses  | AR < 1,000/                                    | AP < 300                                 | μs              |
| Test pulse interval  | Min. 1   | 00                                       | ms              |
| Output voltage U <sub>FO1A</sub> / U <sub>FO1B</sub> 1)  |  |  |                 |
| HIGH U <sub>F01A</sub> / U <sub>F01B</sub>   | U <sub>B</sub> -2V                             | . UR                                     |                 |
| LOW U <sub>F01A</sub> / U <sub>F01B</sub>  | 0  |  | V DC            |
| Switching current per safety output  | 1 2  |  | mA              |
| Switching current per control input IMP1, IMP2   |  |  | 1117 (          |
| and IMM  | 20   | 25                                       | mA              |
| Jtilization category according to EN IEC 60947-5-2   | DC-13 24 V                                     | 200 m/s                                  |                 |
| of the state of th | Caution: outputs must be protected with a free |  |                 |
| Agaitaring outputs   | p-switching, shor                              |  |                 |
| Monitoring outputs   |  |  |                 |
| Output voltage 1)  | U <sub>A</sub> - 2V .                          |  | Λ               |
| Max. load  | Max.   |  | mA<br>V         |
| Rated insulation voltage U <sub>i</sub>  | 30   |  | V               |
| Rated impulse withstand voltage U <sub>imp</sub>   | 1.5  |  | kV              |
| Resilience to vibration  | In acc. with EN IE                             |  |                 |
| Switching frequency  | 0.25   |  | Hz              |
| EMC protection requirements  | In acc. with EN IE                             |  |                 |
| Reliability values acc. to EN ISO 13849-1  | Guard lock monitoring                          | Control of the guard locking             |                 |
| Category   | 4  | 4  |                 |
| Performance Level  | PL e   | PL e                                     |                 |
| PFH <sub>d</sub>   | 3.7 x 10 <sup>-9</sup> / h <sup>2)</sup>       | 2.8 x 10 <sup>-9</sup> / h <sup>2)</sup> |                 |
| Mission time   | 20   | 20                                       | years           |
| B <sub>10d</sub> (emergency stop)  | 0.065 x  |  | ,,,,,,,         |
| Emergency stop   | 5.000 A  | ·  |                 |
| Operating voltage  | 5 2  | 24                                       | V               |
| Operating voltage  |  |  | · ·             |
|  |  |  | mA<br>mW        |
| Breaking capacity max.   | 250  |  | mW              |
|  | 24   |  | V DC            |
|  |  |  |                 |
| Controls and indicators  |  |  |                 |
| Controls and indicators Operating voltage  | UA   |  | V               |
| Controls and indicators Operating voltage Operating current  | UA<br>1 :                                      | 10                                       | V<br>mA         |
| Power supply LED Controls and indicators Operating voltage Operating current Breaking capacity max.  | UA   | 10                                       | -               |

<sup>1)</sup> 2)

Values at a switching current of 50 mA without taking into account the cable length.

Applying the limit value from EN ISO 13849-1:2008, section 4.5.2 (MTTFd = max. 100 years), the employers' liability insurance association certifies a PFHd of max. 2.47 x 10<sup>8</sup>.



#### 13.1. Typical system times



#### Important!

The system times given are maximum values for one device.

#### Ready delay:



In case of AR configuration the following applies: After switching on, the unit carries out a self-test for 10 s. The system is ready for operation only after this time.



In case of AP configuration the following applies: After switching on, the unit carries out a self-test for 0.5 s. The system is ready for operation only after this time.

#### Switch-on time of safety outputs:



In case of AR configuration the following applies: The max. reaction time from the moment when the safety guard is locked to the moment when the safety outputs switch on T<sub>on</sub> is 570 ms.



In case of AP configuration the following applies: The max. reaction time from the moment when the bolt tongue is inserted to the moment when the safety outputs switch on T<sub>on</sub> is 570 ms.



Simultaneity monitoring, safety inputs FI1A/FI1B: If the safety inputs have different switching states for longer than 150 ms, the safety outputs FO1A/FO1B will be switched off. The device switches to fault state.

#### Risk time according to EN 60947-5-3:



With active guard lock monitoring the following applies: If the guard locking is no longer effective, the safety outputs F01A and F01B \rightarrow are deactivated after a maximum of 350 ms.

This value applies to a single switch. For each additional switch in a chain the risk time increases by 5 ms.



With inactive guard lock monitoring the following applies: If the bolt tongue is pulled out of the locking module, the safety outputs F01A and F01B are deactivated after a maximum of 350 ms.

This value applies to a single switch. For each additional switch in a chain the risk time increases by 5 ms.

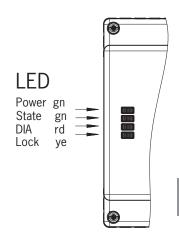
Difference time: The safety outputs FO1A and FO1B switch with a slight delay in relation to each other. They both have the ON state at the latest after a difference time of 10 ms.

**Time offset:** The max, permissible time offset between switch-on of operating voltage UB and auxiliary voltage UA is 1 s.

## 14. System states

## 14.1. Key to symbols

| 0 | LED not illuminated                |
|---|------------------------------------|
| * | LED illuminated                    |
|   | LED flashes for 8 seconds at 10 Hz |
|   | LED flashes three times            |
| X | Any state                          |





## 14.2. MGB-AR system status table

| 14               | .2. MGB-                           | AK S                    | syst                        | em s                          | stati   | ıs ta   | bie   |  |   |   |   |  |   |  |   |  |  |  |   |
|------------------|------------------------------------|-------------------------|-----------------------------|-------------------------------|---|---|---|--|---|---|---|--|---|--|---|--|--|--|---|
|                  | State                              | Selftest after power up | Normal operation, door open | Normal operation, door closed | Normal operation, door closed, bolt tongue inserted safety inputs F11A/F11B OFF | With active guard lock monitoring: Normal operation, door closed, bolt tongue inserted. Safety inputs F11A/F11B are ON. Safety outputs F01A and F01B Hz are OFF | With inactive guard lock monitoring: Normal operation, door closed, bolt tongue inserted. Safety inputs F11A/F11B are ON. Safety outputs F01A and F01B are ON | <b>Operation in an AR chain:</b> Normal operation, door closed and locked. Safety outputs on the previous device OFF | Operation as separate device: Normal operation, door closed and locked.  Operation in an AR chain: Normal operation, door closed and locked. Safety outputs on the previous device ON | Door open; device is ready for teach-in of another handle module (only 3 min. after Power UP) | Teach-in operation, tip: To prevent the interruption of teach-in operations, close door and switch on guard locking | Positive acknowledgment after completion of teach-in operation | Error during teach-in/configuration or invalid DIP switch setting | F11A/F11B input error (e.g. missing test pulses, illogical switching state from previous switch) | Handle module read error (e.g. error in code) | Output fault (e.g., short circuit, loss of switching capability) or short circuit at the outputs | Internal fault (e.g. component faulty, data error) | Signal sequence erroneous (e.g. broken bolt tongue)<br>With active release monitoring: escape release or mechanical release was actuated | Control inputs IMP1, IMP2, IMM invalid; switch control inputs off for min. $^{1}\!\!/_{2}$ s and switch on again to reset |
|                  | Госк (λellow)                      |                         |                             |                               | Long ON,<br>short OFF   |   | short OFF   |  |   |   |   |  |   |  |   |  |  | 1 ×  | 2 x   |
|                  |                                    | 0                       | 0                           | 0                             | *   | ->  | K   | *  | *   | 0   | 0   | 0  | 0   | 0  | 0   | 0  | 0  | *  | *   |
| LED indicator    | (red)                              |                         |                             |                               |   |   | 0   |  |   |   |   |  |   |  | *   | <u> </u>   |  |  | *   |
| LED in           | STATE (green)                      | 2 Hz                    | Long OFF<br>short ON        | Long ON,<br>short OFF         | Long ON,<br>short OFF   | Long ON,<br>short OFF   |   | Long ON,<br>short OFF  |   | ×<br>es   | 1 Hz  |  | 1<br>×  | 2 ×  | 3×<br>8                                       | * 4<br>×   |  |  |   |
|                  |                                    | *                       | *                           | *                             | *   | *   | *   | *  | *   | *   | *   | 0  | 漱   | *  | *   | *  | 0  | 0  | 0   |
|                  | Power (green)                      |                         |                             |                               |   |   | *   |  |   |   |   |  |   |  |   |  |  |  |   |
| gui <sup>-</sup> | Diagnostics monitor<br>output (IO) | OFF                     | OFF                         | OFF                           | OFF   | Ļ   | 5   | OFF  | OFF   | OFF   | OFF   | OFF  | N<br>O  | NO   | OFF   | NO   | NO   | NO   | NO  |
| -yor             | Guard locking monifiated (OL)      | OFF                     | OFF                         | OFF                           | OFF   | L   | 5   | NO   | NO  | OFF   | OFF   | OFF  | OFF   | OFF  | ×   | OFF  | OFF  | OFF  | OFF   |
| gui              | Bolt tongue monitor<br>(TO)        | OFF                     | OFF                         | OFF                           | NO  | 2   | <u>z</u>  | NO   | NO  | OFF   | OFF   | OFF  | OFF   | OFF  | ×   | OFF  | OFF  | OFF  | OFF   |
| tpuť             | Door monitoring out<br>(OD)        | OFF                     | OFF                         | NO                            | NO  | 2   | <u>z</u>  | NO   | NO  | OFF   | OFF   | OFF  | OFF   | OFF  | ×   | OFF  | OFF  | OFF  | OFF   |
| ,                | Safety outputs FO1A                | OFF                     | OFF                         | OFF                           | OFF   | OFF   | NO  | OFF  | NO  | OFF   | OFF   | OFF  | OFF   | OFF  | OFF   | OFF  | ×  | OFF  | ×   |
|                  | Guard locking                      | ×                       | OFF                         | OFF                           | OFF   | Ľ   | 5   | NO   | NO  | OFF   | NO  | ×  | ×   | ×  | ×   | ×  | ×  | ×  | ×   |
|                  | Position of the bolt<br>sugnot     | ×                       | not inserted                | not inserted                  | inserted  | -   | Inserted  | inserted   | inserted  | not inserted  | inserted  | ×  | ×   | ×  | ×   | ×  | ×  | ×  | ×   |
|                  | Door position                      | ×                       | oben                        | closed                        | closed  | -   | closed  | closed   | closed  | uado  | closed  | ×  | ×   | ×  | ×   | ×  | ×  | ×  | ×   |
|                  | Safety outputs FIIA<br>and FIIB    | ×                       | ×                           | ×                             | OFF   |   | 200   | OFF  | NO  | ×   | ×   | ×  | ×   | errone-<br>ous   | ×   | ×  | ×  | ×  | ×   |
|                  | Operating mode                     | Self-test               |                             |                               |   | Normal oper-<br>ation   |   |  |   | Teach-in standby<br>(only for MGB<br>unicode)   | Setup<br>(only for MGB  | unicode)   |   |  |   | Diagnostics  |  |  |   |

After remedying the cause, use the reset function (see chapter 15. Troubleshooting and assistance on page 40) or briefly disconnect the power supply. Please contact the manufacturer if the fault could not be reset after restarting.



## 14.3. MGB-AP system status table

| 14            | .3. MGB-                           | AP s                        | syste                         | em s   | statı   | ıs ta                                     | ble  | ı  |  |   | ı   |   |  | ı   |   |
|---------------|------------------------------------|-----------------------------|-------------------------------|--|---|---|--|--|--|---|---|---|--|---|---|
|               | State                              | Normal operation, door open | Normal operation, door closed | With active guard lock monitoring: Normal operation, door closed, bolt tongue inserted. Safety outputs F01A and F01B ษ are OFF | With inactive guard lock monitoring: Normal operation, door closed, bolt tongue inserted. Safety outputs FO1A and FO1B are ON | Normal operation, door closed and locked. | Door open; device is ready for teachin of another handle module (only 3 min. after Power UP) | Teach-in operation, tip: To prevent the interruption of teachin operations, close door and switch on guard locking | Positive acknowledgment after completion of teach in operation | Error during teach-in/configuration or invalid DIP switch setting | Handle module read error (e.g. error in code) | Output fault (e.g. short circuit, loss of switching capability) or short circuit at the outputs | Internal fault (e.g. component faulty, data error) | Signal sequence erroneous (e.g., broken bolt tongue)<br>With active release monitoring; escape release or mechanical release was actuated | Control inputs IMP1, IMP2, IMM invalid; switch control inputs off for min. ½ s and switch on again to reset |
|               |                                    |                             |                               | Long ON,   |   |   |  |  |  |   |   |   |  | 1 ×   | 2 x   |
|               | Lock (yellow)                      | 0                           | 0                             |  | \$<br>  | *   | 0  | 0  | 0  | 0   | 0   | 0   | 0  | *   | *   |
| icator        | (red)                              |                             | l                             | 0  |   |   |  |  |  |   |   |   |  |   | *   |
| LED indicator | 4                                  | Long OFF<br>short ON        | Long ON,<br>short OFF         | Long ON,<br>short OFF  |   |   | 3×<br>3×   | 1 Hz   |  | 1 ×   | 3×  | 4 ×   |  |   |   |
|               | State (green)                      | *                           | - 36                          |  | *   | *   | *  | *  | 0  | *   | *   | *   | 0  | 0   | 0   |
|               | Power (green)                      |                             | l                             |  |   |   | >  |  |  |   |   | l   |  |   |   |
|               | Diagnostics monitor<br>output (OI) | OFF                         | OFF                           | E  | ±   | OFF                                       | OFF  | 90   | OFF  | N<br>O  | OFF   | NO  | NO NO  | NO  | NO  |
|               | Guard locking monii                | OFF                         | OFF                           | F  | 5   | N <sub>O</sub>                            | OFF  | OFF  | OFF  | OFF   | ×   | OFF   | OFF  | OFF   | OFF   |
| gui           | Bolt tongue monitor<br>output (TO) | OFF                         | OFF                           | 2  | 5   | NO  | OFF  | OFF  | OFF  | OFF   | ×   | OFF   | OFF  | OFF   | OFF   |
| ınd           | Door monitoring out                | OFF                         | NO                            | 2  | <u> </u>  | NO  | OFF  | OFF  | OFF  | OFF   | ×   | OFF   | OFF  | OFF   | OFF   |
| 1             | Safety outputs FO1A<br>and FO1B    | OFF                         | OFF                           | OFF  | NO  | NO  | OFF  | OFF  | OFF  | OFF   | OFF   | OFF   | ×  | OFF   | ×   |
|               | Guard locking                      | OFF                         | OFF                           | Ę  | <u> </u>  | NO  | OFF  | NO   | ×  | ×   | ×   | ×   | ×  | ×   | ×   |
|               | Position of the bolt<br>sugnot     | not inserted                | closed not inserted           | 1  | Inserted  | inserted                                  | not inserted   | inserted   | ×  | ×   | ×   | ×   | ×  | ×   | ×   |
|               | Door position                      | o beu u                     | closed r.                     | 000  | closed  | closed                                    | u uedo   | closed   | ×  | ×   | ×   | ×   | ×  | ×   | ×   |
|               | Operating mode                     |                             |                               | Normal oper-<br>ation  |   |   | Teach-in standby<br>(only for MGB<br>unicode)  | Setup<br>(only for MGB   | unicode)   | Diagnostics   |   |   |  |   |   |

After remedying the cause, use the reset function (see chapter 15. Troubleshooting and assistance on page 40) or briefly disconnect the power supply. Please contact the manufacturer if the fault could not be reset after restarting.

EN



## 15. Troubleshooting and assistance

### 15.1. Fault reset

Proceed as follows:

- 1. Open the safety guard.
- 2. Switch off operating voltage at the locking module for min. 3 seconds or connect 24 V to the input RST for min. 3 seconds.
  - Alternatively, the internal reset (see 7. System overview on page 12) can be pressed for 3 seconds with a pointed object, e.g. ball-point pen.
- → The green LED (State) flashes quickly (approx. 5 Hz in case of AR configuration). A self-test is performed during this time (approx. 10 s in case of AR configuration). The LED then cyclically flashes three times.
- 2. Close safety guard and switch guard locking on.
- → The system is in normal mode again.

## 15.2. Help on troubleshooting in the Internet

You will find a help file on troubleshooting under "Support" in the service area at www.euchner.de.

#### 15.3. Help on mounting in the Internet

You will find an animation on the mounting process at www.euchner.de.

## 15.4. Application examples

You will find application examples on connecting the device to various control systems at www.euchner.de.

## 16. Service

If service support is required, please contact: EUCHNER GmbH + Co. KG Kohlhammerstraße 16 D-70771 Leinfelden-Echterdingen

#### **Service telephone:**

+49 711 7597-500

#### E-mail:

support@euchner.de

#### Internet:

www.euchner.de



## 17. Inspection and service



#### **WARNING**

Loss of the safety function because of damage to the system.

In case of damage, the affected module must be replaced completely. Only accessories or spare parts that can be ordered from EUCHNER may be replaced.

Regular inspection of the following is necessary to ensure trouble-free long-term operation:

- Check the switching function (see section *Electrical function test on page 35*)
- Check the secure fastening of the devices and the connections
- Check for soiling

No servicing is required; repairs to the device are only allowed to be made by the manufacturer.



#### **NOTICE**

The year of manufacture can be seen in the lower right corner of the rating plate.

ΕN



## 18. Declaration of conformity

## More than safety





**EUCHNER** 

EUCHNER GmbH + Co. KG Kohlhammerstraße 16 70771 Leinfelden-Echterdingen Germany

EG-Konformitätserklärung EC-Declaration of Conformity CE-Déclaration de Conformité CE-Dichiarazione di conformità CE-Declaración de Conformidad Original DE Translation EN Traduction FR Traduzione IT Traducción ES

23150-02-02/

Die nachfolgend aufgeführten Produkte sind konform mit den Anforderungen der folgenden Richtlinien (falls zutreffend): The beneath listed products are in conformity with the requirements of the following directives (if applicable): Les produits mentionnés ci-dessous sont conformes aux exigences imposées par les directives suivantes (si valable) I prodotti sotto elencati sono conformi alle direttive sotto riportate (dove applicabili): Los productos listados a continuación son conforme a los requisitos de las siguientes directivas (si fueran aplicables):

| l:  | 2006/42/EG  | Maschinenrichtlinie                          |
|-----|-------------|--|
|     | 2006/42/EC  | Machinery directive                          |
|     | 2006/42/CE  | Directive Machines                           |
|     | 2006/42/CE  | Direttiva Macchine                           |
|     | 2006/42/CE  | Directiva de máquinas                        |
| II: | 2004/108/EG | EMV Richtlinie                               |
|     | 2004/108/EC | EMC Directive                                |
|     | 2004/108/CE | Directive de Compatibilité électromagnétique |
|     | 2004/108/CE | Direttiva EMV                                |
|     | 2004/108/CE | Directiva CEM                                |

Die Schutzziele der Niederspannungsrichtlinie wurden gemäß Anhang I, Nr. 1.5.1 der Maschinenrichtlinie eingehalten. The safety objectives of the Low-Voltage Directive comply with Annex I, No. 1.5.1 of the Machinery Directive.
Les objectifs de sécurité de la Directive Basse Tension sont conformes à l'annexe I, No. 1.5.1 de la Directive Machines Gli obiettivi di sicurezza della Direttiva Bassa Tensione sono conformi a quanto riportato all'allegato I, No. 1.5.1 della Direttiva Macchine. Los objetivos de seguridad de la Directiva de Bajo Voltaje cumplen con el Anexo I, No. 1.5.1 de la Directiva de Máquinas

Folgende Normen sind angewandt: EN 60947-5-3:1999/A1:2005 Following standards are used: b: EN ISO 14119:2013 EN ISO 13849-1:2008 Les normes suivantes sont appliquées: c: Vengono applicate le seguenti norme: EN 60947-5-5:1997/A1:2005 Se utilizan los siguientes estándares:

| Bezeichnung der Bauteile  | Туре    | Richtlinie     | Normen     | Zertifikats-Nr.        |
|---|---------|----------------|------------|------------------------|
| Description of components   | Type    | Directives     | Standards  | No. of certificate     |
| Description des composants  | Type    | Directive      | Normes     | Numéro du certificat   |
| Descrizione dei componenti  | Tipo    | Direttiva      | Norme      | Numero del certificato |
| Descripción de componentes  | Туро    | Directivas     | Estándares | Número del certificado |
| Sicherheitsschalter   | MGB-LAR | )              |            |                        |
| Safety Switches   | MGB-LAP |                |            |                        |
| Interrupteurs de sécurité   | MGB-H   | <b>≻</b> 1, II | a, b, c    | UQS 123125             |
| Finecorsa di sicurezza  | MGB-E   | ·              |            |                        |
| Interruptores de seguridad  | MGB-C   | J              |            |                        |
| Sicherheitsschalter mit Not-Halt-Einrichtungen                      | MGB-LAR | <u> </u>       |            |                        |
| Safety Switches with Emergency-Stop facilities                      | MGB-LAP |                |            |                        |
| Interrupteurs de sécurité avec appareillage arrêt d'urgence         | MGB-H   |                |            | 1100 400405            |
| Finecorsa di sicurezza con dispositivi di arresto di emergenza      | MGB-E   | } I, II        | a, b, c, d | UQS 123125             |
| Interruptores de seguridad con dispositivos de parada de emergencia | MGB-C   |                |            |                        |

Benannte Stelle Notified Body Organisme notifié Sede indicata Entidad citada

TÜV Rheinland Industrie Service GmbH Am Grauen Stein 51105 Köln

Germany

Leinfelden, Februar 2015

EUCHNER GmbH + Co. KG Kohlhammerstraße 16 70771 Leinfelden-Echterdingen Germany

i.A. Dipl.-Ing. Richard Holz Leiter Elektronik-Entwicklung Manager Electronic Development Responsable Développement Électronique Direttore Sviluppo Elettronica Director de desarrollo electrónico

i.A. Dipl.-Ing. (FH) Duc Binh Nguyen Dokumentationsbevollmächtigter Documentation manager Responsable documentation Responsabilità della documentazione Agente documenta

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EUCHNER GmbH + Co. KG Kohlhammerstraße 16 70771 Leinfelden-Echterdingen Tel. +49/711/7597-0 Fax +49/711/753316 www.euchner.de info@euchner.de

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Euchner GmbH + Co. KG Kohlhammerstraße 16 D-70771 Leinfelden-Echterdingen info@euchner.de www.euchner.de

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